

Benha University
Faculty Of Engineering at Shoubra



ECE 122
Electrical Circuits (2)(2016/2017)
Lecture (9)
Transient Analysis (P1)

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Reference Chapter 16

Schaum's Outline Of Theory And Problems Of Electric Circuits
<https://archive.org/details/TheoryAndProblemsOfElectricCircuits>

Circuits Transient Response

- When a circuit is **switched** from one condition to another either by a change in the applied voltage or a change in one of the circuit elements, there is a **transitional period** during which the branch currents and voltage drops change from their former values to new ones
- After this transition interval called the **transient**, the circuit is said to be in the **steady state**.
- Transient analysis: study of circuit behavior in transition phase.

- The steady state values can be determined using circuit laws and complex number theory.
- The transient is more difficult as it involves **differential equations**.

$$a_n \frac{d^n x(t)}{dt^n} + a_{n-1} \frac{d^{n-1} x(t)}{dt^{n-1}} + \dots + a_0 x(t) = f(t)$$

➤ General solution to the differential equation:

$$x_p(t) \qquad x(t) = x_p(t) + x_c(t) \qquad x_c(t)$$

- Particular integral solution (or forced response particular to a given source/excitation)
- Represent the steady-state solution which is the solution to the above non-homogeneous equation

- Complementary solution (or natural response)
- Represent the transient part of the solution, which is the solution of the next homogeneous equation:

$$a_n \frac{d^n x(t)}{dt^n} + a_{n-1} \frac{d^{n-1} x(t)}{dt^{n-1}} + \dots + a_0 x(t) = 0$$

First-Order and Second-Order Circuits

- » First-order circuits contain only a single capacitor or inductor
- » Second-order circuits contain both a capacitor and an inductor

Differential equations Solutions

- Two techniques for transient analysis that we will learn:
 - ✓ Differential equation approach.
 - ✓ Laplace Transform approach.
- Laplace transform method is a much simpler method for transient analysis

1st Order R-L

DC

First-Order RL Transient Step-Response

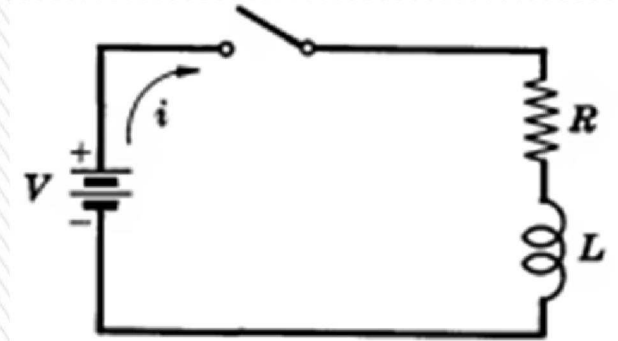
- The switch “S” is closed at $t = 0$
- Apply KVL to the circuit in figure:

$$Ri + L \frac{di}{dt} = V$$

- Rearranging and using “D” operator notation :

$$\left(D + \frac{R}{L}\right)i = \frac{V}{L}$$

This Equation is a first order, linear differential equation



1. Complementary (Transient) Solution

The auxiliary equation is : $m + \frac{R}{L} = 0$

$$i = Ae^{mt} = Ae^{\frac{-R}{L}t}$$

$$\tau = \frac{R}{L}$$

Time constant

2. Particular (Steady-State) Solution

The steady-state value of the current for DC source is :

$$I_{ss} = \frac{V}{R}$$

First-Order RL Transient Step-Response

➤ The total solution is:

$$i = Ae^{\frac{-R}{L}t} + \frac{V}{R}$$

Since The initial current is zero:

$$0 = A + \frac{V}{R}$$

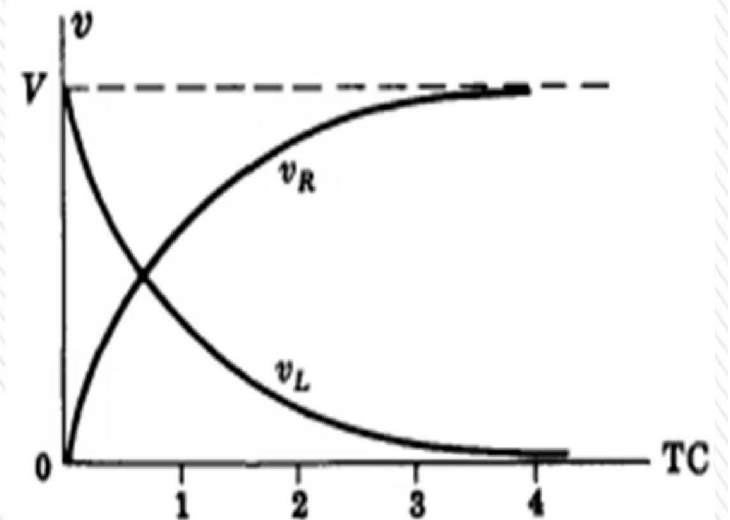
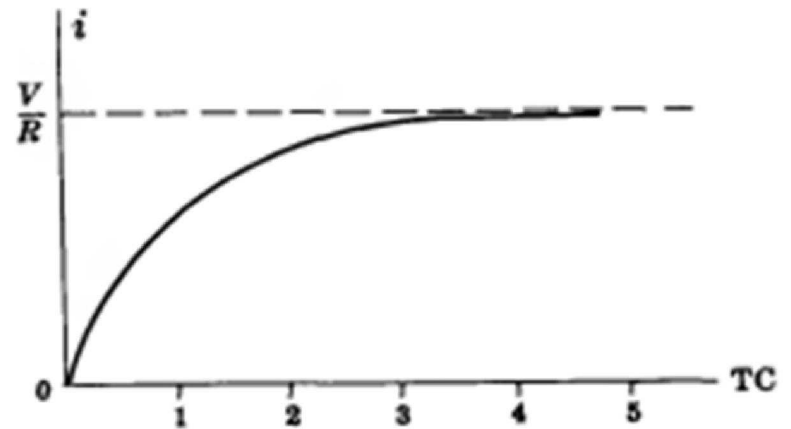
$$i = -\frac{V}{R}e^{-(R/L)t} + \frac{V}{R} = \frac{V}{R}(1 - e^{-(R/L)t})$$

➤ The voltage across the resistor is:

$$v_R = Ri = V(1 - e^{-(R/L)t})$$

➤ The voltage across the inductor is:

$$v_L = L \frac{di}{dt} = L \frac{d}{dt} \left\{ \frac{V}{R}(1 - e^{-(R/L)t}) \right\} = Ve^{-(R/L)t}$$



$$v_R + v_L = V(1 - e^{-(R/L)t}) + Ve^{-(R/L)t} = V$$

1st Order R-L

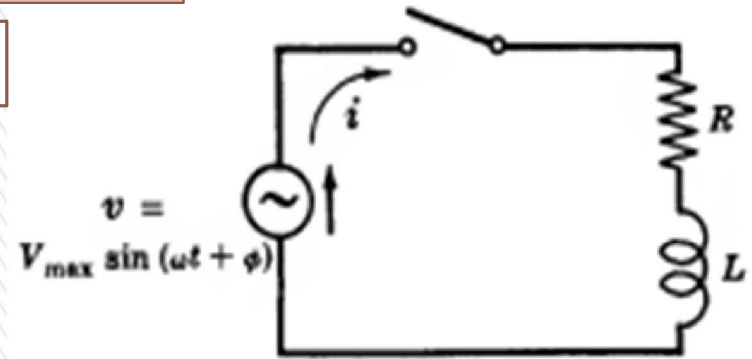
AC

Alternating Current Transients

RL Sinusoidal Transient

$$Ri + L \frac{di}{dt} = V_{\max} \sin(\omega t + \phi)$$

$$\left(D + \frac{R}{L}\right)i = \frac{V_{\max}}{L} \sin(\omega t + \phi)$$



1. Complementary (Transient) Solution is the solution of the homogeneous 1st order DE

The same as before, The auxiliary equation is :

$$m + \frac{R}{L} = 0$$

The complementary function is $i_c = ce^{-(R/L)t}$

2. Particular (Steady-State) Solution

The steady-state value of the current for ac source is :

$$I_{ss} = \frac{V_{\max}}{\sqrt{X_L^2 + R^2}} \sin(\omega t + \phi - \tan^{-1}(\omega L / R))$$

Alternating Current Transients

RL Sinusoidal Transient

The complete solution is

$$i = i_c + i_p = ce^{-(R/L)t} + \frac{V_{\max}}{\sqrt{R^2 + \omega^2 L^2}} \sin(\omega t + \phi - \tan^{-1} \omega L/R)$$

Use the initial condition to find the value of c

$$i_0 = 0 = c(1) + \frac{V_{\max}}{\sqrt{R^2 + \omega^2 L^2}} \sin(\phi - \tan^{-1} \omega L/R)$$

$$c = \frac{-V_{\max}}{\sqrt{R^2 + \omega^2 L^2}} \sin(\phi - \tan^{-1} \omega L/R)$$

Substituting by the constant values, we get:

$$i = e^{-(R/L)t} \left[\frac{-V_{\max}}{\sqrt{R^2 + \omega^2 L^2}} \sin(\phi - \tan^{-1} \omega L/R) \right] + \frac{V_{\max}}{\sqrt{R^2 + \omega^2 L^2}} \sin(\omega t + \phi - \tan^{-1} \omega L/R) \quad (5)$$

Examples

Examples

A series RL circuit with $R = 50$ ohms and $L = 10$ h has a constant voltage $V = 100$ v applied at $t = 0$ by the closing of a switch. Find (a) the equations for i , v_R and v_L , (b) the current at $t = .5$ seconds and (c) the time at which $v_R = v_L$.

(a) The differential equation for the given circuit is

$$50i + 10 \frac{di}{dt} = 100 \quad \text{or} \quad (D + 5)i = 10$$

the complete solution is $i = i_c + i_p = ce^{-5t} + 2$

At $t = 0$, $i_0 = 0$ and $0 = c(1) + 2$ or $c = -2$. Then

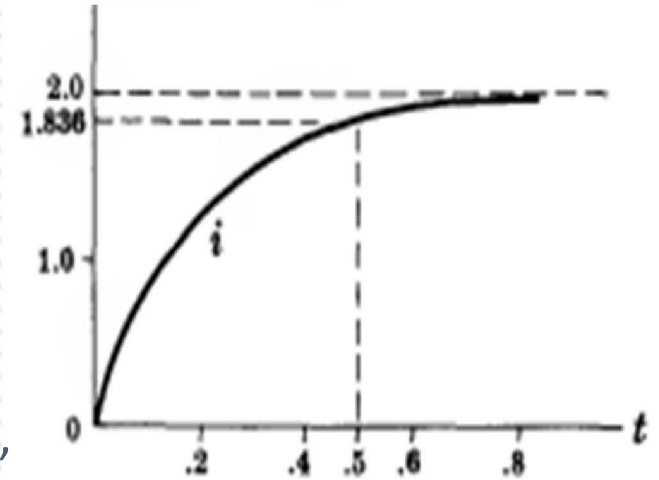
$$i = 2(1 - e^{-5t})$$

$$v_R = Ri = 100(1 - e^{-5t})$$

$$v_L = L \frac{di}{dt} = 100e^{-5t}$$

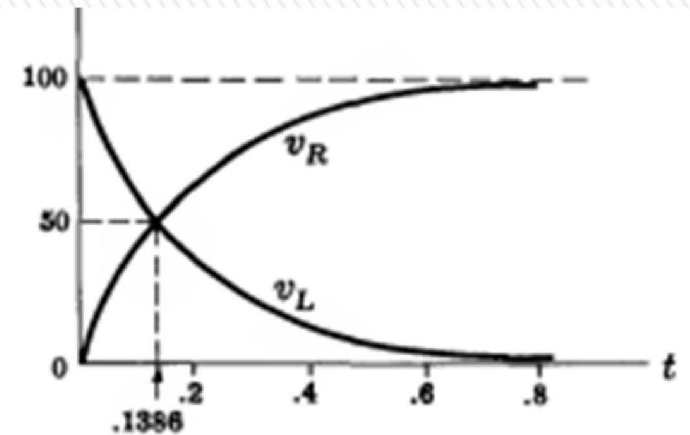
Examples

(b) Put $t = .5$ sec in (3) and obtain $i = 2(1 - e^{-5(.5)}) = 2(1 - .082) = 1.836$ amp.



(b) For the two voltage to be equal:
each must be 50 volts since the applied voltage is 100,

$$\begin{aligned}v_L = 50 &= 100e^{-5t}, \\e^{-5t} = .5 &\text{ or } 5t = .693, \\t &= .1386 \text{ sec.}\end{aligned}$$



Example (2)

In the series circuit shown in Fig.1 the switch is closed on position 1 at $t = 0$, thereby applying the 100 volt source to the RL branch, and at $t = 500 \mu\text{sec}$ the switch is moved to position 2. Obtain the equations for the current in both intervals and sketch the transient.

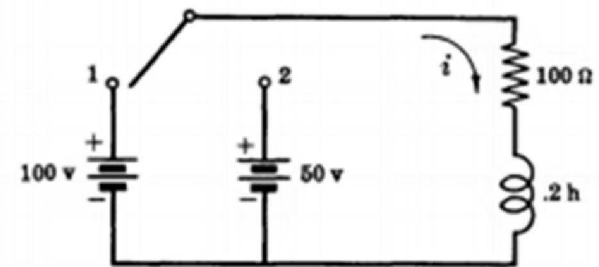
at Pos. 1

$$+100 = 100i + 0.2 \frac{di}{dt}$$

$$500 = 500i + di/dt$$

$$(D + 500)i = 500$$

$$i_{t_1} = 1 + A e^{-500t}$$



cap. sol.
 $D=0 \quad i=1$
 p.i sol.
 $0 = 100 + 500i \rightarrow i = -500$
 $\therefore A e^{-500t} + 1 = i_t$

at $t=0 \quad i_0=0 \quad A=-1$

$\therefore i_{t_1} = 1 - e^{-500t} \rightarrow I \quad \text{for } 0 < t < t_1$

at $t = 500 \mu\text{sec} \quad i = 1 - e^{-500 \times 500 \times 10^{-6}} = 0.221 \text{ A}$

Example (2)

Switch now at position 2, $V_{source} = 50V$

$$\infty \quad 50 = 100i + 0.2 \frac{di}{dt}$$

$$\text{or } (D + 500) = 250$$

$$i_{t_2} = 0.5 + B e^{-500 t_2}$$

$$\text{where } t_2 = t - t_1 \quad \rightarrow 500 \text{MS}$$

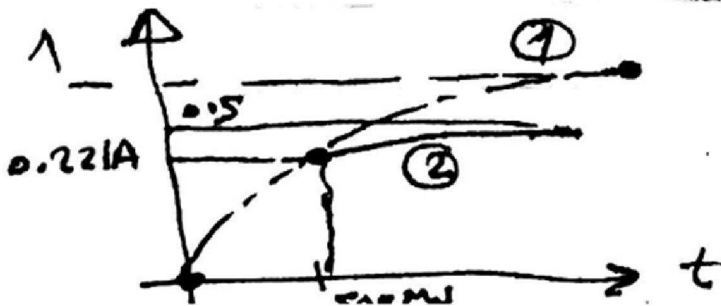
at $t = t_1 \Rightarrow t_2 = 0$, $i_2 = 0.221A$

$$\therefore 0.221A = 0.5 + B \quad \therefore \boxed{B = -0.279}$$

for $t > t_1$ \therefore

$$i_{t_2} = 0.5 - 0.279 e^{-500(t-t_1)}$$

\rightarrow for ~~$t > t_1$~~ $t > t_1$



Example (3)

A series RL circuit with $R = 50$ ohms and $L = 0.2$ H has a sinusoidal voltage source $v = 150 \sin(500t + \phi)$ applied at a time when $\phi = 0$. Find the complete current.

$$Ri + L \frac{di}{dt} = v$$

$$50i + 0.2 \frac{di}{dt} = 150 \sin 500t$$

$$\therefore (D + 250)i = 750 \sin 500t$$

~~complementary sol. $i_c = e^{-250t}$~~
Use Final equation = $C e^{-250t} + i_p$

$$i = \frac{V_{\max}}{P \sqrt{R^2 + \omega^2 L^2}} \sin(\omega t + \phi - \tan^{-1}(\frac{\omega L}{R}))$$

$$= \frac{150}{\sqrt{(50)^2 + (500)^2(0.2)^2}} \sin(500t + 0 - \tan^{-1}(\frac{500 \times 0.2}{50}))$$

$$i(t) = C e^{-250t} + 1.34 \sin(500t - 63.4^\circ)$$

$$\text{at } t=0, \quad i=0$$

$$\therefore 0 = C + 1.34 \sin(-63.4)$$

$$\therefore C = 1.2$$

$$\therefore i_t = 1.2 e^{-250t} + 1.34 \sin(500t - 63.4^\circ)$$

Thank You

